## ECE 204 Numerical methods

## Evaluating a polynomial ata point and Horner's fule

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## Introduction

- In this topic, we will
- Describe the representation of polynomials
- Discuss the idea of evaluating polynomials
- Look at a sequence of more efficient implementations
- We will use C++
- Describe the evaluation of polynomials in MATLAB


## Representing a polynomial

- As with our representation, in C++, we will represent a polynomial as an array where a[k] is the coefficient of $x^{k}$

$$
a_{n} x^{n}+a_{n-1} x^{n-1}+\cdots+a_{2} x^{2}+a_{1} x+a_{0}
$$

- For example:

$$
\text { double a[3]\{ 2.0, 3.0, } 1.0 \text { \}; // } x^{\wedge} 2+3 x+2
$$

## Representing a polynomial

- In MATLAB, a polynomial is represented with a vector:
- An $n$-dimensional vector is polynomial of degree $n-1$
- If p is an $n$-dimensional vector, $\mathrm{p}(\mathrm{k})$ is the coefficient of $x^{n-k}$
- Consequently, the following represents $x^{2}+3 x+2$

$$
\text { >> } p=\left[\begin{array}{lll}
1 & 3 & 2
\end{array}\right] ;
$$

- If a vector is passed to a function expecting a polynomial, the vector is interpreted as described above:
>> roots( p ) ans =
-2
-1


## Representing a polynomial

- Some other useful polynomial functions in Matlab:
>> polyder ( $\left[\begin{array}{lll}1 & 3 & 2\end{array}\right]$ ) \% take the derivative ans =

23
>> polyint( $\left[\begin{array}{lll}1 & 3 & 2\end{array}\right]$ ) \% find the antiderivative ans =
$0.3333 \quad 1.5000 \quad 2.0000 \quad 0$

## Evaluating a polynomial

- Suppose you have the polynomial

$$
1.2 x^{4}-3.8 x^{3}+4.9 x^{2}-0.7 x+5.6
$$

- How would you evaluate this at $x=2.5$ ?
- Author a function pow( double x , unsigned int n ) and call it


## Evaluating a polynomial

- The most expensive way of calculating $x^{n}$ :

```
template <typename T>
T pow_O_n( T x, int n ) {
    if ( n >= 0 ) {
        T result{ 1.0 };
        x n}=\mp@subsup{\underbrace}{n\mathrm{ time }}{x\cdotx\cdotx\cdotsx
        for ( int k{1}; k <= n; ++k ) {
        result *= x;
        }
        return result;
    } else if ( n == INT_MIN ) {
        return pow_0_n( 1.0/x, -(n + 1) )/x;
        x n}=(\frac{1}{x}\mp@subsup{)}{}{-n
    } else {
        return pow_0_n( 1.0/x, -n );
    }
}

\section*{Evaluating a polynomial}
- The most expensive form:
```

template <typename T>
T polyval_0_n2( T coeffs[], unsigned int degree, T x ) {
T result{ coeffs[0] };
for ( unsigned int k{1}; k <= degree; ++k ) {
result += coeffs[k]*pow_0_n( x, k );
}
return result;
}

```

\section*{Evaluating a polynomial}
- A recursive means of calculating \(x^{n}\) :
```

template <typename T>
T pow_O_ln_n_rec( T x, int n ) {
if ( n > 0 ) {
T result{ pow_0_ln_n_rec( x, n/2 ) };
result *= result;
return ( (n\&1) == 0 ) ? result : result*x;
} else if ( n == 0 ) {
return 1.0;
} else if ( n == INT_MIN ) {
return pow_0_ln_n_rec( 1.0/x, -(n + 1) )/x;
} else {
return pow_0_ln_n_rec( 1.0/x, -n );
}
}

```

\section*{Evaluating a polynomial}
- A more efficient approach:
```

template <typename T>
T polyval_O_n_ln_n_rec( T coeffs[], unsigned int degree, T x ) {
T result{ coeffs[0] };
for ( unsigned int k{1}; k <= degree; ++k ) {
result += coeffs[k]*pow_0_ln_n_rec( x, k );
}
return result;
O(n\operatorname{ln}(n))
}

```

\section*{Evaluating a polynomial}
- An iterative means of calculating \(x^{n}\) :
template <typename T>
```

T pow_O_ln_n_iter( T x, int n ) {
if ( n >= 0 ) {
T result{ 1.0 };
x}21=\mp@subsup{x}{}{16+4+1}=\mp@subsup{x}{}{16}\mp@subsup{x}{}{4}\mp@subsup{x}{}{1
for ( ; n > 0; n <<= 1, x *= x ) {
if ( (n\&1) == 1 ) {
result *= x;
}
}}\textrm{O}(\operatorname{ln}(n)
return result;
} else if ( n == INT_MIN ) {
return pow_0_ln_n_iter( 1.0/x, -(n + 1) )/x;
} else {
return pow_0_ln_n_iter( 1.0/x, -n );

```
    \}
\}

This \(\mathrm{C}++\) code is meant to demonstrate sub-optimal algorithms not required on the examination

\section*{Evaluating a polynomial}
- An even more efficient approach:
```

    template <typename T>
    T polyval_O_n( T coeffs[], unsigned int degree, T x ) {
    T result{ coeffs[0] };
    T term{ 1.0 };
    ```
    for ( unsigned int \(k\{1\}\); \(k<=\) degree; ++k ) \{
        term *= x;
        result += coeffs[k]*term;
    \}
    return result;
\}
- A total of approximately \(3 n\) FLOPS

\section*{Evaluating a polynomial}
- All these evaluate the polynomial in the standard form
\[
1.2 x^{4}-3.8 x^{3}+4.9 x^{2}-0.7 x+5.6
\]
- What about rewriting it?
\[
\begin{aligned}
& (1.2 x-3.8) x^{3}+4.9 x^{2}-0.7 x+5.6 \\
& ((1.2 x-3.8) x+4.9) x^{2}-0.7 x+5.6 \\
& (((1.2 x-3.8) x+4.9) x-0.7) x+5.6
\end{aligned}
\]
- This has only \(2 n\) FLOPS
- This is known as Horner's rule for evaluating polynomials

\section*{Evaluating a polynomial}
- This has approximately half the run time of the previous version: template <typename T> T polyval_horner( T coeffs[], unsigned int degree, T x ) \{ T result\{ coeffs[degree] \};
```

for ( unsigned int k{degree - 1}; k <= degree; --k ) {
result = result*x + coeffs[k];
}
return result;

## Evaluating a polynomial

- This implementation is approximately $1 \%$ faster:

```
template <typename T>
```

T polyval horner ptr( T coeffs[], unsigned int degree, T x ) \{
T *coefff coeffs + degree \};
T result\{ *coeff \};
while (coeff > coeffs ) \{
result = x*result + *--coeff;
\}
return result;
\}

- If you require such efficiency, use assembly language...


## Horner's rule

- In MATLAB, evaluating a polynomial is straight-forward:

```
>> p = [llll
>> polyval( p, 0.3 ); % calculate p(0.3)
    ans =
            2.9900
>> polyval( [1 3 2], [0.3 0.2; 0.5 -0.1] )
    ans =
    2.9900 2.6400
    3.7500 1.7100
```


## Summary

- Following this topic, you now
- Understand the representation of polynomials that:
- We will use for C++
- Is used in MatLab
- Have seen successively more efficient evaluations of polynomials
- Are aware that this ends with the very efficient Horner's rule
- Know that in MATLAB,
calling polyval will evaluate the polynomial using Horner's rule


## References

[1] https://en.wikipedia.org/wiki/Horner\'s_method
[2] https://www.mathworks.com/help/matlab/polynomials.html

## Acknowledgments

None so far.

## Colophon

These slides were prepared using the Cambria typeface. Mathematical equations use Times New Roman, and source code is presented using Consolas. Mathematical equations are prepared in MathType by Design Science, Inc.
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The photographs of flowers and a monarch butter appearing on the title slide and accenting the top of each other slide were taken at the Royal Botanical Gardens in October of 2017 by Douglas Wilhelm Harder. Please see https://www.rbg.ca/
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